

**Trigonometric Bézier and
Stancu Polynomials**



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Abstract. We introduce a family of trigonometric polynomials, denoted as Stancu polynomials, which covers as special cases the trigonometric Lagrange and Bernstein polynomials. This family depends only on one real parameter, denoted as *design parameter*. Our approach works for curves as well as for surfaces over triangles. The resulting Stancu curves resp. surfaces therefore establish a link between trigonometric interpolatory and Bernstein-Bézier curves resp. surfaces.

Keywords. Trigonometric Lagrange polynomials, trigonometric Bernstein polynomials, Stancu polynomials, design parameter.

Guido Walz
Fakultät für Mathematik und Informatik
Universität Mannheim
D-68131 Mannheim
Germany
walz@math.uni-mannheim.de

0. Introduction

Recently, trigonometric splines and polynomials have gained very much interest within CAGD, in particular curve design, see for example Alfeld, Neamtu, Schumaker (1995), Koch, Lyche, Neamtu, Schumaker (1995), Gonsor & Neamtu (1996), Peña (1996), Walz (1997). The aim of the present note is twofold: First, similarly as done in the (algebraic) polynomials case in Farin & Barry (1986) and Walz (1988, 1991), we introduce a one-parameter family of trigonometric polynomials, which provides a link between the trigonometric Lagrange polynomials (1.1) and Bernstein polynomials (1.2). Then, in section 2, this approach will be transferred to trigonometric polynomials (in barycentric coordinates) on a triangle.

1. Stancu Polynomials on an Interval

We consider, for even integer n , the $(n+1)$ -dimensional space of trigonometric polynomials

$$\mathcal{T}_m := \text{span}\{1, \cos(2\tau), \sin(2\tau), \dots, \cos(n\tau), \sin(n\tau)\}$$

where $0 \leq \tau \leq 1$. The *Lagrange* polynomials (w.r.t. equidistant nodes) from \mathcal{T}_m are the functions

$$l_\nu(\tau) = \prod_{\substack{j=0 \\ j \neq \nu}}^n \frac{\sin(\tau - \frac{j}{n})}{\sin(\frac{\nu-j}{n})}, \quad \nu = 0, \dots, n, \quad (1.1)$$

whereas the corresponding *Bernstein* polynomials are

$$b_\nu(\tau) = \frac{\sin^\nu(\tau) \cdot \sin^{n-\nu}(1-\tau)}{\sin^n(1)}, \quad \nu = 0, \dots, n. \quad (1.2)$$

Both sets of functions form a basis of \mathcal{T}_m . Moreover, since $l_\nu(\frac{\mu}{n}) = \delta_{\mu\nu}$ for $\mu, \nu = 0, \dots, n$, the trigonometric polynomial (curve)

$$L(\tau) = \sum_{\nu=0}^n d_\nu l_\nu(\tau) \quad (1.3)$$

interpolates the points d_0, \dots, d_n , whereas the trigonometric Bernstein-Bézier curve

$$B(\tau) = \sum_{\nu=0}^n d_\nu b_\nu(\tau) \quad (1.4)$$

possesses nice shape-preserving properties.

We now make the following construction: With a real parameter a , $0 \leq a \leq \frac{1}{n}$, and the variable τ we set

$$\varphi_k(\tau) := \prod_{j=0}^{k-1} \sin(\tau - ja), \quad (1.5)$$

for $k \in \mathbb{N}$, and $\varphi_0 \equiv 1$. Then, for each $\nu \in \{0, \dots, n\}$, the trigonometric polynomial

$$s_\nu(\tau, a) := \frac{\varphi_\nu(\tau, a) \cdot \varphi_{n-\nu}(1-\tau, a)}{\varphi_\nu(\tau_a, a) \cdot \varphi_{n-\nu}(\tau_a, a)}, \quad (1.6)$$

where $\tau_a := 1 - a(n+1)$, is denoted as ν^{th} *Stancu polynomial*. Obviously, $s_\nu \in \mathcal{T}_m$. Moreover, the following result holds:

Theorem 1: a) For each parameter value $0 \leq a \leq \frac{1}{n}$, it is

$$\mathcal{T}_m = \text{span}\{s_0(\cdot, a), \dots, s_n(\cdot, a)\}.$$

b) For each $\nu \in \{0, \dots, n\}$, we have

$$s_\nu(\tau, a) = \begin{cases} b_\nu(\tau) & \text{for } a = 0, \text{ and} \\ l_\nu(\tau) & \text{for } a = \frac{1}{n}. \end{cases}$$

Proof. We consider the relation

$$\sum_{\nu=0}^n c_\nu s_\nu(\tau, a) = 0 \quad \text{for } \tau \in [0, 1]. \tag{1.7}$$

In particular, (1.7) must hold for $\tau = 0$. Since $s_\nu(0, a) = 0$ for $\nu = 1, \dots, n$, it follows that c_0 must be zero. Analogously, setting $\tau = a, 2a, \dots, (n-1)a$, it follows successively that $c_1 = \dots = c_n = 0$. This proves the linear independence of the functions s_ν and therefore statement a). Statement b) can be verified by straightforward calculation. \square

Theorem 1 shows in particular that the *trigonometric Stancu Curve*

$$S(\tau, a) = \sum_{\nu=0}^n d_\nu s_\nu(\tau, a) \tag{1.8}$$

establishes a link between the interpolatory and the shape preserving curves (1.3) and (1.4). The real parameter a should be denoted as *design parameter*.

2. Stancu Polynomials over a Triangle

In this section we transfer the idea described in Section 1 to the case of bivariate trigonometric polynomials over a triangle. So, as a special case, we will also obtain trigonometric triangular Bernstein Bézier polynomials. The corresponding (algebraic) polynomials were introduced and investigated in (Farin, 1986) resp. (Walz, 1991).

As usual, we describe a point P on a given fixed triangle $\langle T_1, T_2, T_3 \rangle$ by its barycentric coordinates (τ_1, τ_2, τ_3) , i.e.,

$$\begin{aligned} P &= \tau_1 T_1 + \tau_2 T_2 + \tau_3 T_3, \\ 1 &= \tau_1 + \tau_2 + \tau_3. \end{aligned}$$

We will use the index set

$$N_n := \{(\nu_1, \nu_2, \nu_3) \in \mathbb{N}_0^3; \nu_1 + \nu_2 + \nu_3 = n\}$$

with $\binom{n+2}{2}$ elements. Then, with the auxiliary functions φ_k and the point τ_a from above, we define for each $(\nu_1, \nu_2, \nu_3) \in N_n$ the *Stancu polynomial* over a triangle as

$$s_{(\nu_1, \nu_2, \nu_3)}(P, a) := \frac{\varphi_{\nu_1}(\tau_1, a) \cdot \varphi_{\nu_2}(\tau_2, a) \cdot \varphi_{\nu_3}(\tau_3, a)}{\varphi_{\nu_1}(\tau_a, a) \cdot \varphi_{\nu_2}(\tau_a, a) \cdot \varphi_{\nu_3}(\tau_a, a)}. \tag{2.1}$$

The following theorem, which also can be proved by straightforward calculation, shows that this one-parameter family of functions contains the trigonometric Bernstein polynomials

$$b_{(\nu_1, \nu_2, \nu_3)}(P) = \frac{\sin^{\nu_1}(\tau_1) \cdot \sin^{\nu_2}(\tau_2) \cdot \sin^{\nu_3}(\tau_3)}{\sin^n(1)} \tag{2.2}$$

as well as the trigonometric Lagrange polynomials

$$l_{(\nu_1, \nu_2, \nu_3)}(P) = \prod_{j_1=0}^{\nu_1-1} \frac{\sin(\tau_1 - \frac{j_1}{n})}{\sin(\frac{j_1+1}{n})} \cdot \prod_{j_2=0}^{\nu_2-1} \frac{\sin(\tau_2 - \frac{j_2}{n})}{\sin(\frac{j_2+1}{n})} \cdot \prod_{j_3=0}^{\nu_3-1} \frac{\sin(\tau_3 - \frac{j_3}{n})}{\sin(\frac{j_3+1}{n})} \tag{2.3}$$

over triangles as special cases.

Theorem 2: For each $(\nu_1, \nu_2, \nu_3) \in N_n$, we have

$$s_{(\nu_1, \nu_2, \nu_3)}(P, a) = \begin{cases} b_{(\nu_1, \nu_2, \nu_3)}(P) & \text{for } a = 0, \text{ and} \\ l_{(\nu_1, \nu_2, \nu_3)}(P) & \text{for } a = \frac{1}{n}. \end{cases}$$

Corollary: For each set of $\binom{n+2}{2}$ points $\{d_{(\nu_1, \nu_2, \nu_3)}; (\nu_1, \nu_2, \nu_3) \in N_n\}$, the surface

$$L(P) := \sum_{(\nu_1, \nu_2, \nu_3) \in N_n} d_{(\nu_1, \nu_2, \nu_3)} \cdot l_{(\nu_1, \nu_2, \nu_3)}(P)$$

possesses for all $(i_1, i_2, i_3) \in N_n$ the interpolation property

$$L\left(\frac{i_1}{n}, \frac{i_2}{n}, \frac{i_3}{n}\right) = d_{(i_1, i_2, i_3)}.$$

Proof. Follows from the fact that for all (i_1, i_2, i_3) and $(\nu_1, \nu_2, \nu_3) \in N_n$,

$$l_{(\nu_1, \nu_2, \nu_3)}\left(\frac{i_1}{n}, \frac{i_2}{n}, \frac{i_3}{n}\right) = \begin{cases} 1, & \text{if } (i_1, i_2, i_3) = (\nu_1, \nu_2, \nu_3), \\ 0, & \text{otherwise.} \end{cases}$$

□

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Guido Walz
Fakultät für Mathematik und Informatik
Universität Mannheim
D-68131 Mannheim
Germany
walz@math.uni-mannheim.de

